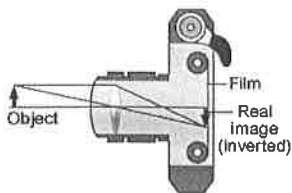


Applications

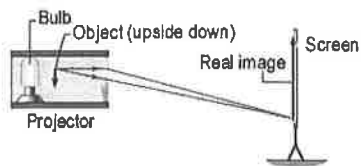
State the type of lens, locate the object and image, and describe the image for each device below.

a) Camera



Lens: converging
 Object: beyond $2F$
 Image: between $F + 2F$
 smaller, inverted
 + real

b) Projector



Lens: converging
 Object: inside $F + 2F$
 Image: beyond $2F$
 larger, real, inverted

c) Magnifying Glass



(convex)
 Lens: converging
 Object: inside F
 Image: virtual, larger
 + upright

d) Security "Peephole"



(concave)
 Lens: diverging
 Object: anywhere
 Image: smaller, upright
 + virtual

The Thin-Lens Equation and Linear Magnification

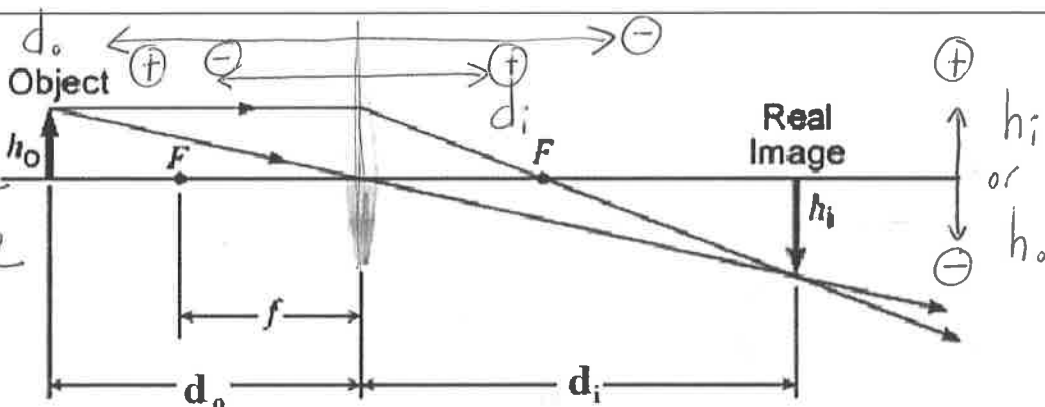
f = focal length

d_o or u = object distance

d_i or v = image distance

h_o = object height

h_i = image height



Thin-Lens Equation

$$\frac{1}{f} = \frac{1}{d_o} + \frac{1}{d_i}$$

Linear Magnification

$$M = \frac{d_i}{d_o} = \frac{h_i}{h_o}$$

Sign Conventions

positive = real
 negative = virtual

1. A 3.0 cm high object is placed 15 cm from a converging lens whose focal length is 6 cm . Determine the location of the image and describe its properties. Determine the magnification of the lens and the height of the image.

$$d_i = \left(\frac{1}{f} - \frac{1}{d_o} \right)^{-1}$$

$$M = -\frac{d_i}{d_o}$$

$$h_i = M \times h_o$$

$d_i = 10 \text{ cm}$
 real image

$M = -\frac{2}{3}$
 smaller

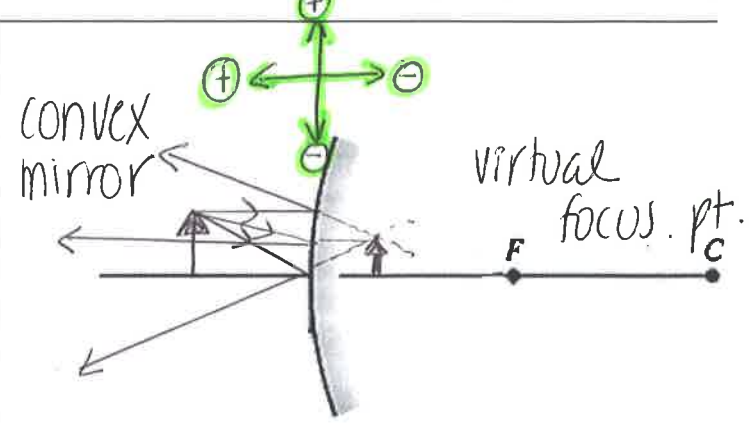
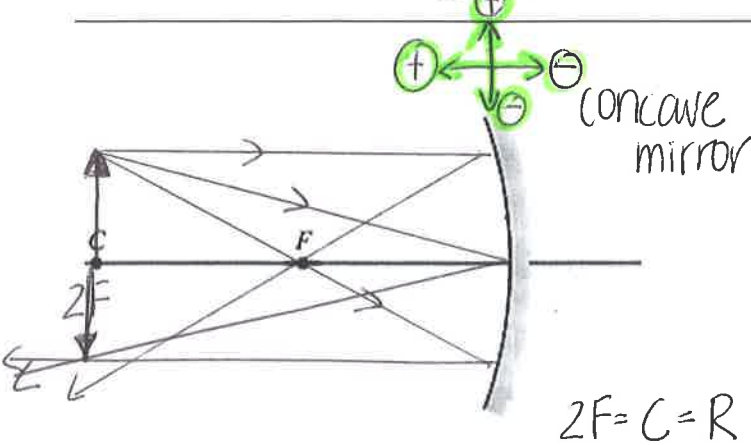
$\left(-\frac{2}{3} \right) (3.0 \text{ cm})$
 $h_i = -2 \text{ cm}$
 inverted

⊕ real image ⊖ virtual image

Comparisons – Mirrors and Lenses

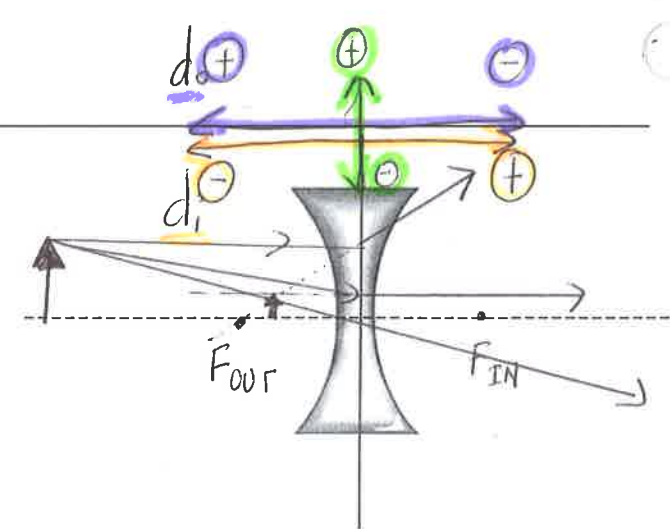
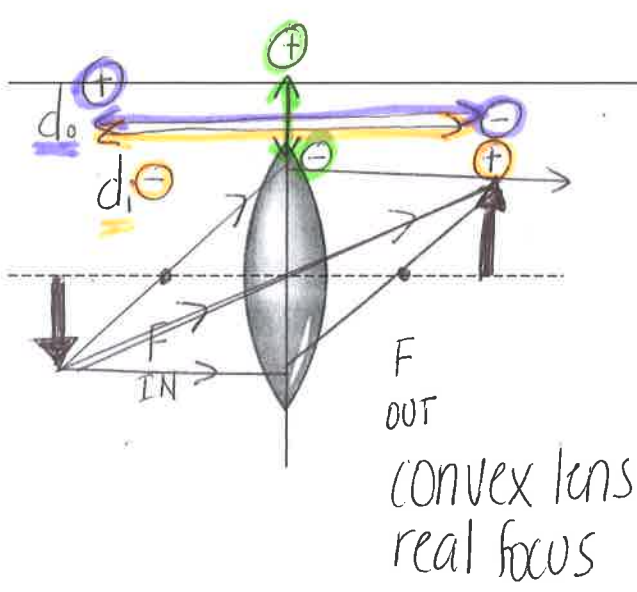
Converging

Diverging



- 1) In \parallel , out F.
 - 2) In F, out \parallel .
 - 3) In center, out center.
- At $2F = A + 2F$
 $d_o \quad d_i$

image = smaller
 virtual
 upright



- 1) In \parallel , out F_{OUT}
- 2) In F_{IN} , out \parallel
- 3) In center, out center

image is : virtual
 smaller
 upright